

# Vincenzo Giovanni Comito

vincenzo.comito@gmail.com | Cell : +39 328 8141 693

## EDUCATION

### POLYTECHNIC OF TURIN

M.ENG. IN MECHATRONIC ENGINEERING

110/110

2015 - 2018 | Turin, Italy

Master Thesis @ Objective Software

**A ROS-based Platform for Autonomous Vehicle:  
Foundations and Perception** - S. Barrera, V. Comito

### POLYTECHNIC OF TURIN

B.ENG. IN COMPUTER ENGINEERING

110/110

2012 - 2015 | Turin, Italy

## LINKS

Github: [github.com/clynamen](https://github.com/clynamen)

LinkedIn: [in/vincenzocomito](https://in.linkedin.com/in/vincenzocomito)

## SKILLS

- Embedded software, Real Time
- ROS (Robot Operating System)
- Server-side development on PaaS.
- Data Science and Machine Learning tools (R and Python)
- Long time linux user.

## PROGRAMMING

Knowledge of:

C, C++, C++14, C#, Java, Python, Javascript

Familiarity with:

Scala, Ruby, R, Julia, Rust

Basic knowledge of:

Haskell

## LANGUAGES

Italian (Mother tongue)

English (Cambridge FCE)

German (Goethe-Zertifikat A2)

## EXPERIENCE

### OBJECTIVE SOFTWARE | SOFTWARE DEVELOPER

October 2016 - Ongoing | Turin, Italy

Objective is a consulting company focused on Automotive. While providing expertise in ECU development, the firm is involved in autonomous-driving, teleoperated-driving projects. Enjoying the flexibility demand of the job, I worked both as low and high level programmer in many projects.

- Teleoperated driving hardware and software integration
- Embedded development on body domain unit (C++, Autosar)
- Computer Vision tools and systems

### KIWI B2B | JUNIOR SERVER DEVELOPER

October 2013 - October 2014 | Turin, Italy

Kiwi was a company that provided a location-based social network addressed to both the general public and companies. I worked as a Java, then C# backend developer.

- Implemented new API endpoints
- Worked on migration after PaaS change
- Libraries used: Objectify, Hibernate, Memcached, Guava, Guice, Entity Framework

## ACTIVITIES

### TEAM DIANA

November 2012 - October 2016 | Turin, Italy

Team D.I.A.N.A. is a student team at Polytechnic of Turin focused on space rovers. I worked on SLAM algorithms and control software of an engineering model of a lunar rover. I had the chance to lead the team for two years, along with fantastic, relentless students. The team uses ROS, C++ and python extensively, interfacing with motors, stereo and depth cameras. More details about the project can be found at <http://www.teamdiana.it/>

## MOOC

Machine Learning	Stanford University
Statistical Learning	Stanford University
Cryptography I	Stanford University
Computer Graphics	UC San Diego

## INTERESTS

I am mainly interested in machine learning and computer vision. In my free time I also like to read about computer security, game development and work with functional programming languages.